## A-0645

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Roll No. .....

# **MT-610**

# M.A./M.Sc. MATHEMATICS (MAMT/MSCMT) (Mathematical Programming-II)

4th Semester Examination, Session December 2024

Time : 2:00 Hrs.

Max. Marks: 70

Note :- This paper is of Seventy (70) marks divided into Two (02) Sections 'A' and 'B'. Attempt the questions contained in these Sections according to the detailed instructions given therein. *Candidates* should limit their answers to the questions on the given answer sheet. No additional (B) answer sheet will be issued.

#### Section-A

### Long Answer Type Questions 2×19=38

Note :- Section 'A' contains Five (05) Long-answer type questions of Nineteen (19) marks each. Learners are required to answer any two (02) questions only.

**A–645/MT–610** (1) P.T.O.

1. Solve the non-linear programming problem by Kuhn-Tucker conditions :

Optimize :

$$Z = 4x_1^2 + 2x_2^2 + x_3^2 - 4x_1x_2$$

subject to the constraints :

$$x_1 + x_2 + x_3 = 15$$
$$2x_1 - x_2 + 2x_3 = 20$$

2. Use Wolfe's method to solve the Quadratic Programming Problem :

Maximize :

$$\mathbf{Z} = 2x_1 + 3x_2 - 2x_1^2$$

subject to the constraints :

$$x_1 + 4x_2 \le 4$$
$$x_1 + x_2 \le 2$$
$$x_1, x_2 \ge 0$$

3. Solve the following quadratic programming problem by using Beale's method.

Maximize :

$$\mathbf{Z} = 4x_1 + 6x_2 - x_1^2 - 3x_2^2$$

**A–645/MT–610** (2)

subject to the constraints :

$$x_1 + 2x_2 \le 4$$
  
and  $x_1, x_2 \ge 0$ 

4. Use separable convex programming to solve the nonlinear programming problem :

Maximize :

and

$$f(x) = 3x_1 + 2x_2$$

subject to the constraints :

$$g(x) = 4x_1^2 + x_2^2 \le 16$$
$$x_1, x_2 \ge 0$$

5. What is meant by quadratic programming ? How does quadratic programming problem differ from the linear programming problem ? Discuss one method and solving it.

#### Section-B

#### Short Answer Type Questions 4×8=32

- Note :- Section 'B' contains Eight (08) Short-answer type questions of Eight (08) marks each. Learners are required to answer any *four* (04) questions only.
- **A–645/MT–610** (3)

- 1. Write short notes on :
  - (a) Quadratic programming
  - (b) Dynamic programming
- 2. Derive the Kuhn-Tucker conditions for an optimal solution to a quadratic programming problem.
- 3. Discuss about duality in quadratic programming.
- Discuss briefly four applications of non-linear programming problem.
- 5. Give the computational procedure for Beale's method for solving Quadratic programming problem.
- 6. What do you mean by convex separable programming ? How will you solve the separable non-linear programming problem :

Minimize :

$$\Sigma f_{oj}(x_j)$$

subject to constraints :

$$\sum f_{oi}(x_i) \ge b_i$$
  $(j = 1, 2, ..., n)$ 

7. Explain Bellman's optimality principle.

**A–645/MT–610** (4)

8. Mention briefly the Wolfe's algorithm for solving a quadratic programming problem given in the usual notations :

Maximize :

$$\mathbf{Z} = cx + \frac{1}{2} x^{\mathrm{T}} \mathbf{Q} x$$

such that  $Ax \le b$  and  $x \ge 0$ , T is transpose.

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